

# Introduction to Synchronization

Frequency, Time, and Phase

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Derek Kozel

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# Introduction

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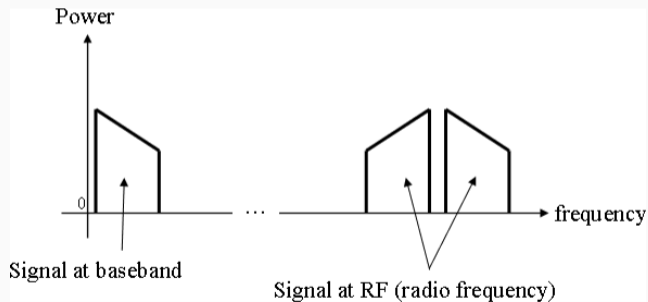
- GNU Radio has many DSP synchronization blocks, not talking about them
- Synchronization of the physical radio(s)
- Frequency, Time, Phase
- Overview of the problem

# Frequency

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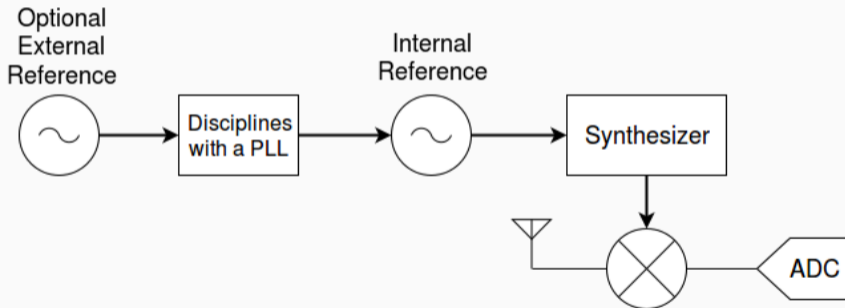
## CARRIER FREQUENCY

- Baseband signals are mixed with a carrier for transmission
- Carrier has frequency and phase information
- Received signals are mixed with a carrier generated locally

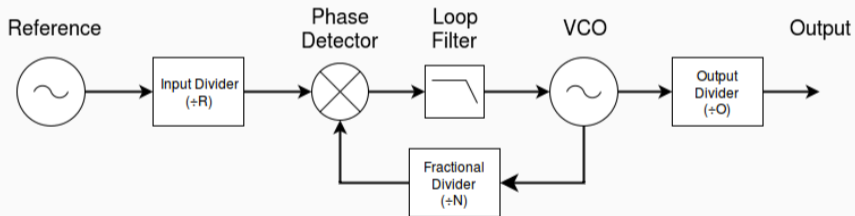


## CARRIER GENERATION

- Frequency accuracy and stability depends on the reference oscillator
- Usually a fractional-N based synthesizer



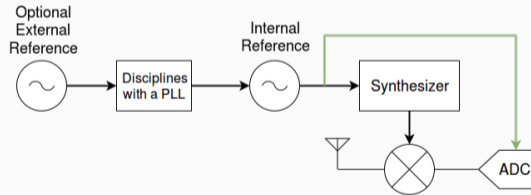
- Generate output frequencies from a reference using a control loop comparing phases





## SAMPLE CLOCKS

- ADCs and DACs often accept external clock signals
- Sampling clock offsets present as time shifts
- Sampling clock jitter presents as phase noise



$$\text{Fractional Frequency Error} = \frac{\text{Frequency}_{\text{measured}} - \text{Frequency}_{\text{nominal}}}{\text{Frequency}_{\text{nominal}}}$$

Source	Accuracy	Error <sup>1</sup>
Crystal	$10^{-5}$	1 Hz at 100 kHz
TCXO	$10^{-6}$	1 Hz at 1 MHz
OCXO	$10^{-8}$	1 Hz at 100 MHz
Rubidium	$10^{-11}$	1 Hz at 100 GHz
Cesium	$10^{-14}$	1 Hz at 100 THz

<sup>1</sup><https://www.febo.com/pages/stability/>

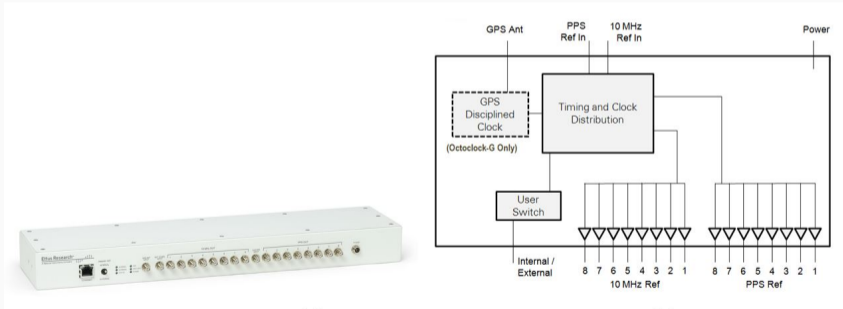
Time

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- Many applications require high precision timestamps
- Timestamping on the host is degraded by processing and transport latency
- Useful, or essential, to have time available on the device
- Tuning, Antenna switching, start/stop of sampling

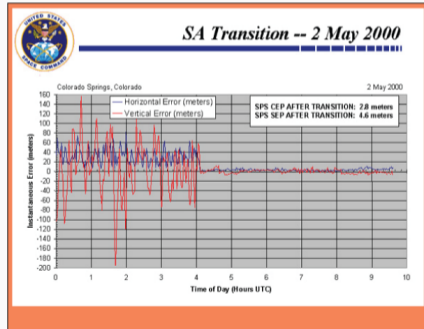
# 1 PULSE PER SECOND

- Precision timing source
- Commonly output by GPSDOs



# GPS TIME REFERENCES

- Globally available time reference
- 10-50 nS accuracy
- Good enough for frequency and (usually) time synchronization
- At 200 MSPS equates to a 2-10 sample error
- Can be onboard or external



Phase

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# PHASE SYNCHRONIZATION

- Remember, we're talking about physical phase synchronization
- Beamforming, Direction Finding, self cancellation have strict phase synchronization requirements

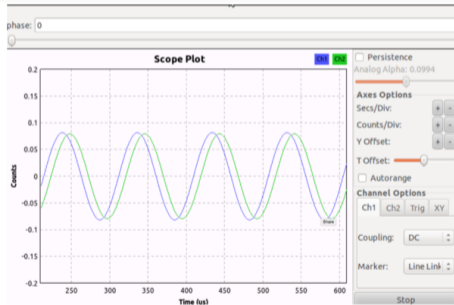


Figure 7- Time Domain Display Showing Received Signal before Phase Compensation

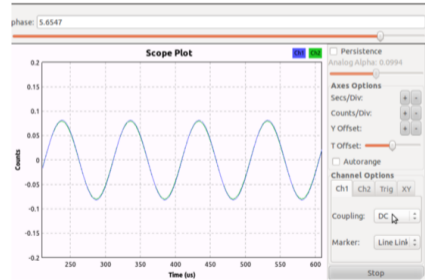
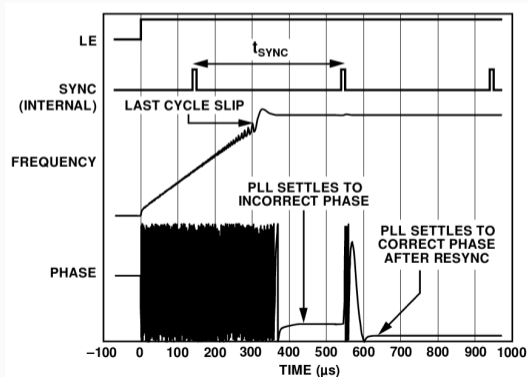


Figure 8- Time Domain Display Showing Received Signal with Phase Compensation



## SYNTHESIZERS REVISITED

- Phase ambiguities introduced because of dividers and architecture
- Many synthesizers can synchronize their output signal's phase with respect to the input reference
- Sometimes automatic, sometimes requires external signals

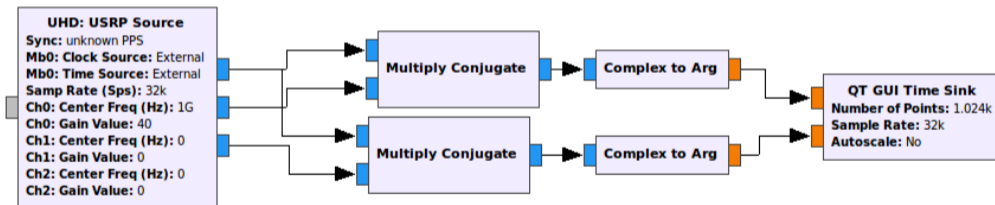


- Phase synchronization is always between two or more signals
- Requires frequency synchronization first
- Requires time synchronization (or shared signals) for commands to the synths

- Even with frequency and time alignment and phase resync offsets may still exist
- Differences in layout between channels on multichannel receivers, cable lengths, thermal...
- Easy to calibrate as long as offsets are constant across tunes and power cycles

## PHASE OFFSET MEASUREMENT

- Multiplying one signal by the complex conjugate of another gives the offset
- A correction can be applied to each signal using a multiplication



## Conclusion

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- Different applications require different levels of synchronization
- Shared physical references are convenient but still require attention to detail
- GNU Radio has a variety of DSP based synchronization utilities

Questions?

The latest version of these slides can always be found at  
<http://www.derekkozel.com/talks>

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`github.com/matze/mtheme`

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